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VARIABLE LIST

RCW-M, WIRELESS RECEIVER



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Variable list, Wireless receiver RCW-M

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Chapter 1 RCW-M, Wireless receiver with Modbus communication

1.1 Introduction

The wireless receiver communicates with up to 16 wireless sensors and detectors.

RCW-M is a Modbus slave that uses RTU (see below 1.1.1 and 1.1.2)

The variable list is a compilation of all the variables that can be read and variables that can be changed in the wireless system.

1.1.1 Modbus protocol in general

The Modbus protocol is a general-purpose protocol for data exchange between for instance control units, SCADA systems, instruments, and electricity meters. It's an asynchronous, serial Master Slave protocol. It's widely used, well documented and simple to understand.

A Modbus master can communicate with up to 247 slave units with the device ID 1-247.

A protocol like Modbus consists of several layers (OSI-model). The bottom layer is always the physical layer; the number of wires and signal levels. The next layer describes the communication digits (number of data bits, stop-bits, parity etc.). Next are the layers describing the Modbus-specific functions (number of digits per message, the meaning of different messages, etc.).

1.1.2 RTU/ASCII modes

The Modbus protocol has two modes: binary (RTU) or character based (ASCII). In RTU mode all registers are transferred in binary format with two hexadecimal digits (0x00-0xFF) in each byte. In ASCII mode, the registers are transferred with one ASCII character (0-9, A-F) in each byte, and therefore twice as many bytes are needed compared to RTU format. On the other hand, the ASCII format has defined start of message and end of message characters which gives faster and more reliable detection of start and end of each message and is not so sensitive to delay in the messages. According to the Modbus standard all devices must have the RTU mode implemented.

RCW-M is a Modbus slave that uses RTU.

RTU character format:

- 1 start bit
- 8 data bits
- Odd, even or no parity bit
- 1 or 2 stop bits. Normally if no parity is used then 2 stop bits should be used.
- Check sum: 16 bits CRC

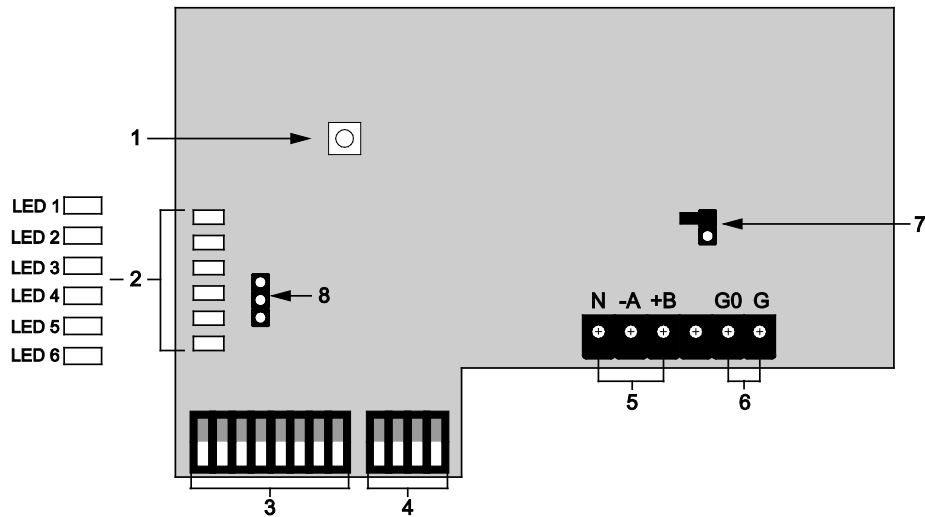
1.1.3 Modbus register types

- 1 = Coil Status Register (Modbus function = 1, 5 and 15)
- 2 = Discrete Input (Modbus function = 2)
- 3 = Holding Register (Modbus function = 3, 6 and 16)
- 4 = Input Register (Modbus function = 4)

Supported Modbus functions:

- 2 = Read Discrete Input
- 3 = Read Holding Register
- 4 = Read Input Register
- 6 = Write Single Register
- 16 = Write Multiple Registers

I.2 RCW-M



| Number | Description | Number | Description |
|--------|---------------------------|--------|----------------------------------|
| 1 | Communication/Test button | 5 | RS485 terminal |
| 2 | LED lights | 6 | Power terminal |
| 3 | DIP switch set 2 | 7 | RS485 terminal resistor (jumper) |
| 4 | DIP switch set 1 | 8 | Service connection |

Table 1

I.3 Configuration

The receiver has two sets of DIP-switches for configuration.

Set 1: RS-485 Parity and Baud rate setting

| Function | Switch 1 | Switch 2 | Value |
|----------|----------|----------|-------|
| Parity | Off | Off | None* |
| | On | Off | Even* |
| | Off | On | None* |
| | On | On | Odd* |

*1 or 2 stop bits

| Function | Switch 3 | Switch 4 | Value |
|-----------|----------|----------|-------|
| Baud rate | Off | Off | 9600 |
| | On | Off | 19200 |
| | Off | On | 38400 |
| | On | On | 38400 |

Table 2

Set 2: Receiver Modbus device ID setting

| DIP-switch | Bit | Position |
|------------|------|----------|
| 1 | Bit0 | On |
| 2 | Bit1 | On |
| 3 | Bit2 | On |
| 4 | Bit3 | On |
| 5 | Bit4 | On |
| 6 | Bit5 | On |
| 7 | Bit6 | On |
| 8 | Bit7 | On |

Table 3

I.4 Pairing sensors to the receiver with Modbus (register 47001-47016)

Up to 16 sensors and/or detectors can be connected to one receiver.

Connect/pair one sensor at the time.

Use function F16 "Pre-set Multiple Registers"

1. Set "Holding register" 47001 to **1** to pair a sensor in zone 1. All 6 LED will start flashing.
2. Press the Test button on your sensor. If the pairing was successful, you will hear a short beep from the receiver, and LED 1 will light up. The sensor is now connected to zone 1.
3. To pair a sensor to zone 2, set Modbus register 47002 to 1 and so on (up to 47016).

Note: If more than 4 sensors are connected, all LEDs will shine. You will not see any difference on the LEDs when you pair more units.

I.4.2 Delete sensors from the receiver with Modbus

1. Set "Holding register" 47001 to **3** to delete the sensor in zone 1.
2. To delete a unit in zone 2, set Modbus register 47002 to 3 and so on (up to 47016)

| Value | Function |
|-------|-----------------------------|
| 1 | Connect/Add to zone |
| 3 | Disconnect/Delete from zone |

Table 4

I.5 Sensor device ID (register 37101-37116)

Every sensor and detector has a label with a unique serial number. The 4-digit device ID is imbedded in the serial number, written in hexadecimal code. The Modbus register displays the device ID in decimal code. To identify the device in the Modbus register, you have to recalculate the hexadecimal value to its decimal value.

The 4-digit hexadecimal ID is located after the first two digits in the serial number, see picture below.



Device ID in Hexadecimal form

This example:
0ECA = Device ID 3786

I.6 Device type (register 37001-37016)

| Name | Description | Device type |
|------------|-------------------------------------|-------------|
| DCW | Wireless door contact | 10 |
| IRW / IRCW | Wireless IR detector | 21 |
| TG-R5W | Wireless room temperature sensor | 100 |
| TG-R6W | Wireless outdoor temperature sensor | 120 |
| EPRW | Wireless optical pulse counter | 200 |

Table 5

I.7 Setting "wake-up" times (register 40101-40116)

The "wake-up" time for a sensor, i.e. the time interval when the sensor collects information from the surroundings, can be set via Modbus. The factory setting is 2 minutes.

Note: If the wake-up time is changed, the battery life will change as well.

Chapter 2 Variable list

2.1 Discrete Input

| Modbus register | Device | Description |
|-----------------|--------------|--------------------------|
| 10001-10016 | DCW/IRW | DCW/IRW condition |
| 10101-10116 | All | Sensor low battery alarm |
| 10201-10216 | DCW/IRW/IRCW | Sensor tamper alarm |
| 10301-10316 | All | Sensor supervision alarm |

Table 6

2.2 Input registers

| Modbus register | Device | Description | Unit | Scale |
|-----------------|------------------|---|------|-------|
| 30001-30016 | TG-R5W TG-R6W | Temperature | °C | 100 |
| 30101-30116 | EPRW | Power | Watt | |
| 30201-30232 | EPRW | Energy (2 registers/channel) | kWh | 10 |
| 37001-37016 | All | Device type (see 1.7 above) | | |
| 37101-37116 | All | Device Id of connected device (see 1.6 above) | | |
| 37201-37216 | All | RSSI signal strength | dB | -1 |
| 37301-37316 | All | RSSI min signal strength 48 Hour (worst level the last 48 hours) | dB | -1 |
| 39001-39020 | All | F/W version | | |

Table 7

2.2 Holding registers

| Modbus register | Device | Description | Unit | Scale |
|-----------------|---------------|--|---------|-------|
| 40001-40016 | DCW / IRW | Counter for DI | | |
| 40101-40116 | TG-R5W/TG-R6W | Wake up time (Adjustable: R/W) | Seconds | 10 |
| 40201-40232 | EPRW | Energy (2 registers/channel) | kWh | 10 |
| 40301-40316 | EPRW | Pulse counter | Imp/kWh | |
| 47001-47016 | All | Commission device (see 1.4) Decommission device (see 1.4.2) | | |

Table 8

| Modbus register | Device | Description | Unit | Default |
|-----------------|------------------|-----------------------------------|-------------|---------|
| 49001 | IRW / IRCW | Time for active on-signal | Seconds | 5 |
| 49002 | DCW / IRW / IRCW | Supervision time out (min. 7200s) | Seconds | 14400 |
| 49003 | EPRW | Supervision time out (min. 7200s) | Seconds | 14400 |
| 49004 | TG-R5W / TG-R6W | Supervision time out (min. 7200s) | Seconds | 14400 |
| 49006 | TG-R5W / TG-R6W | Default wake up time | Seconds x10 | 12 |
| 49007 | EPRW | Default imp/kWh | Imp/Kwh | 1000 |
| 49010 | All | The time left of 48Hrs (RSSI) | Minutes | - |
| 49011 | RCW-M | EPRW reporting time | Seconds | 300 |

Table 9